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## A semi-automated algorithm to quantify similarity between outsole impressions using SURF

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## **A semi-automated algorithm to quantify similarity between outsole impressions using SURF**

### **Disciplines**

Forensic Science and Technology

### **Comments**

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# Similarity between outsole impressions using SURF

Soyoung Park, Alicia Carriquiry



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Center for Statistics and  
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# It takes a village



## Collaborators:

- Dr. Hari Iyer, NIST
- Sarena Wiesner, Yaron Shor, Israeli Police
- Dr. Guillermo Basulto-Elias, Mr. James Kruse, CSAFE
- Ms. Lesley Hammer, Hammer Forensics
- Dr. Eric Hare, Omni Analytics
- A small army of super smart undergraduates, Iowa State University.

# Goals of presentation



- Introduce an objective method to quantify the similarity between two outsole impressions.
- Show that algorithm is accurate and reliable even when outsoles share class characteristics and degree of wear.
- Show that algorithm is robust even when one image is degraded and partially observed.

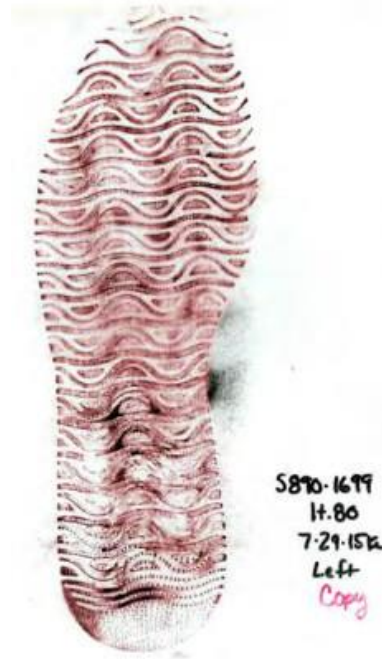
# The forensic question

Could the shoe on  
the left be the  
source of the  
impression on the right?

Q = questioned

K = known

**Challenging!**



# The state of the art



- At present, practitioners rely on training and experience to:
  - Identify features of interest that can be used to compare outsoles.
  - Subjectively determine whether outsoles are “similar enough” to suggest same source.
- Two implicit assessments:
  - How similar are the outsoles?
  - How probative is observed degree of similarity.

# Can we do better?



- Develop a (semi-)automated algorithm that:
  - Identifies features of interest in outsoles.
  - Compares their values across the two impressions.
  - Computes a *similarity score*.
- Ideally, the similarity score is:
  - Large, when impressions are made by the same shoe.
  - Small, otherwise.



# Rich literature

- Bodziak, WJ. 2000. CRC Press.
- Stone, RS. 2006. *J For Ident.*
- Patil, PM., Kulkarni, JV. 2009. *Pattern Recognition.*
- Algarni, G., Hamiani, M. 2008. *For Sci Int.*
- Kortylewski, A. et al. 2014. *Asian Conf Comp Vision.*
- Gwo, CY, Wei, CH. 2016. *Sci & Just.*
- Alizadeh, S., Kose, C. 2017. *For Sci Int.*
- Bodziak, WJ. 2017. CRC Press.
- Richetelli, N., et al. 2017. *For Sci Int.*
- Park, S., Carriquiry, A. 2019. Revision requested, *JCGS.*
- *MANY MORE*



# Data



- CSAFE built a database with 160 pairs of shoes.
- Two models: Nike Airflow and Adidas Seeley.
- Four sizes: 8, 8.5, 10, 10.5.
- Participants received a pair of new shoes with a step counter.
- Returned every 6-8 weeks so that shoe outsoles could be photographed and imaged. [Everos 2D scanner.]
- For each shoe: 4 sets of replicated measurements over a 6-month period.
- **To download: [www.forensicstats.org/data](http://www.forensicstats.org/data).**

# Outsole photos



All Nike (Adidas) shoes share class characteristics and degree of wear.

# Algorithm I

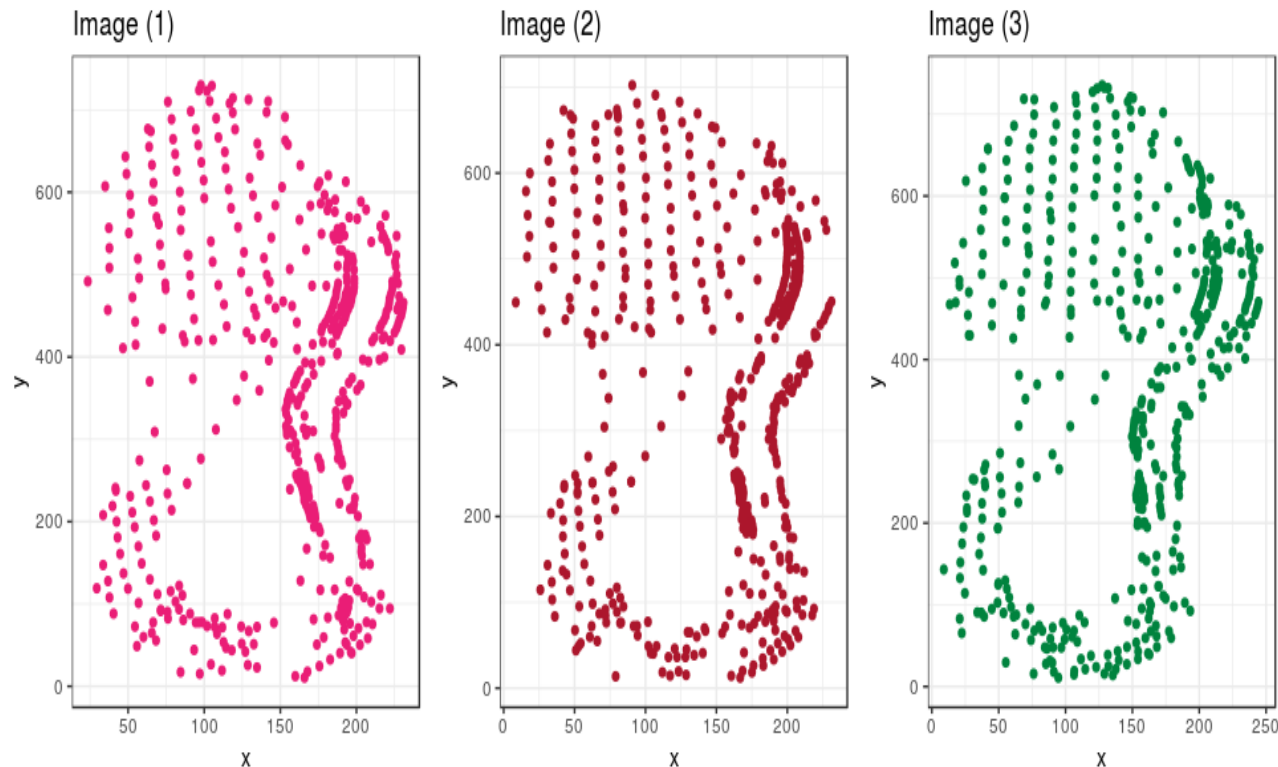


- We started out with 2D images of 60 pairs of Nike shoe outsoles with about 6 months of wear.
- Each shoe was imaged 4 times.
- Data: The x-y coordinates of the pixels that form the image.
- Each image has thousands of pixels.
- First step: Identify *interesting points* in each image.

# Algorithm II - SURF



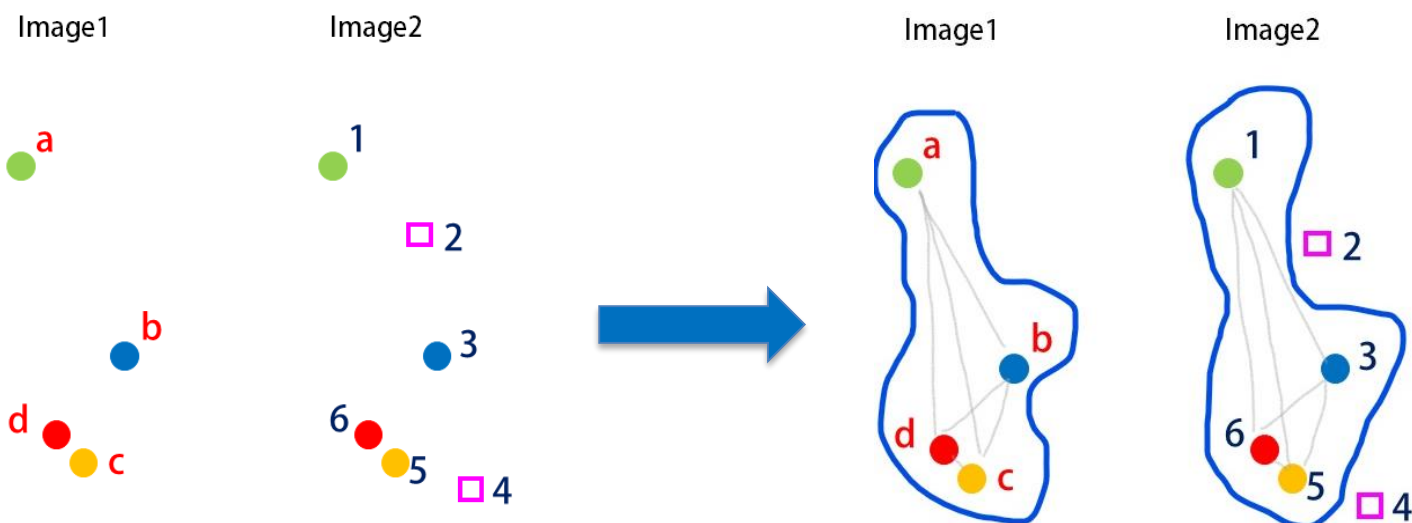
- We used 500 SURF (Speeded-Up Robust Features, Bay et al. , 2006) as the points of interest.



# Algorithm III -Alignment



- To align two images Q and K we find the ***maximum clique***: set of points in Q and K that have the same geometric arrangement.
- The MC is invariant to rotation and translation.



# Algorithm IV - Alignment

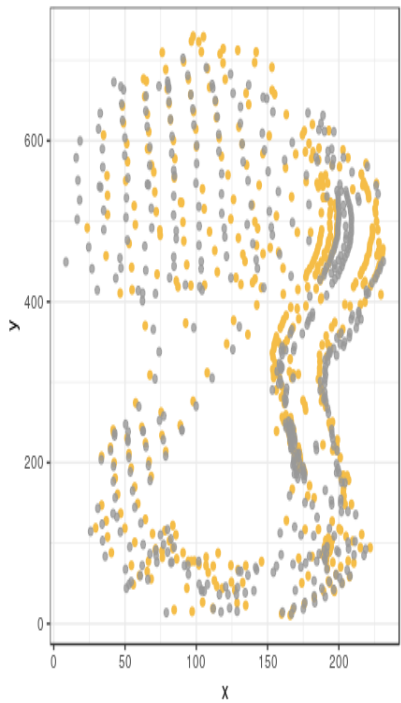


- Once the  $MC_Q$  and the  $MC_K$  have been found, the algorithm computes the rotation angle and translation matrix needed to overlay  $MC_Q$  onto  $MC_K$ .
- These estimates are then used to align all other points on the images.
- Computationally expensive but effective.

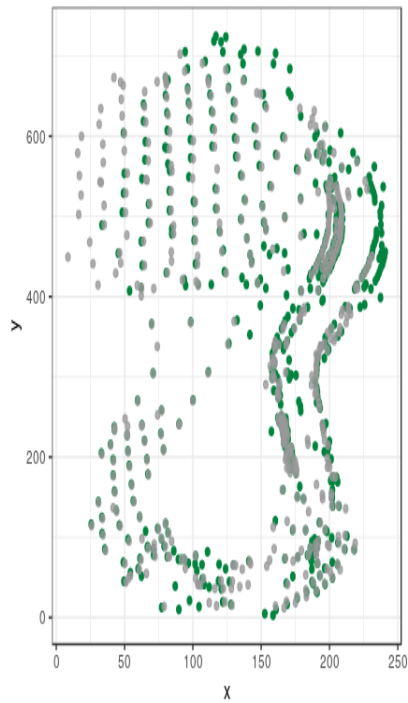
# Aligned images



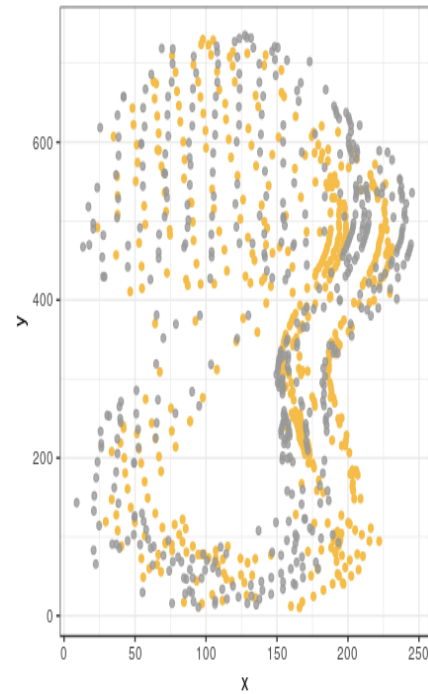
Mates-before aligning



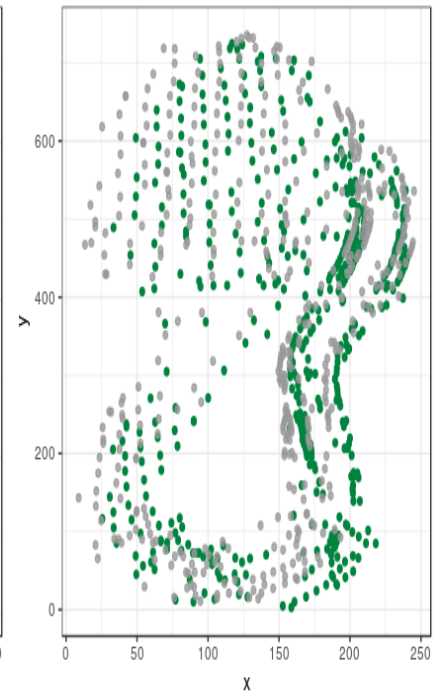
Mates-after aligning



Nonmates-before aligning



Nonmates-after aligning





# Features



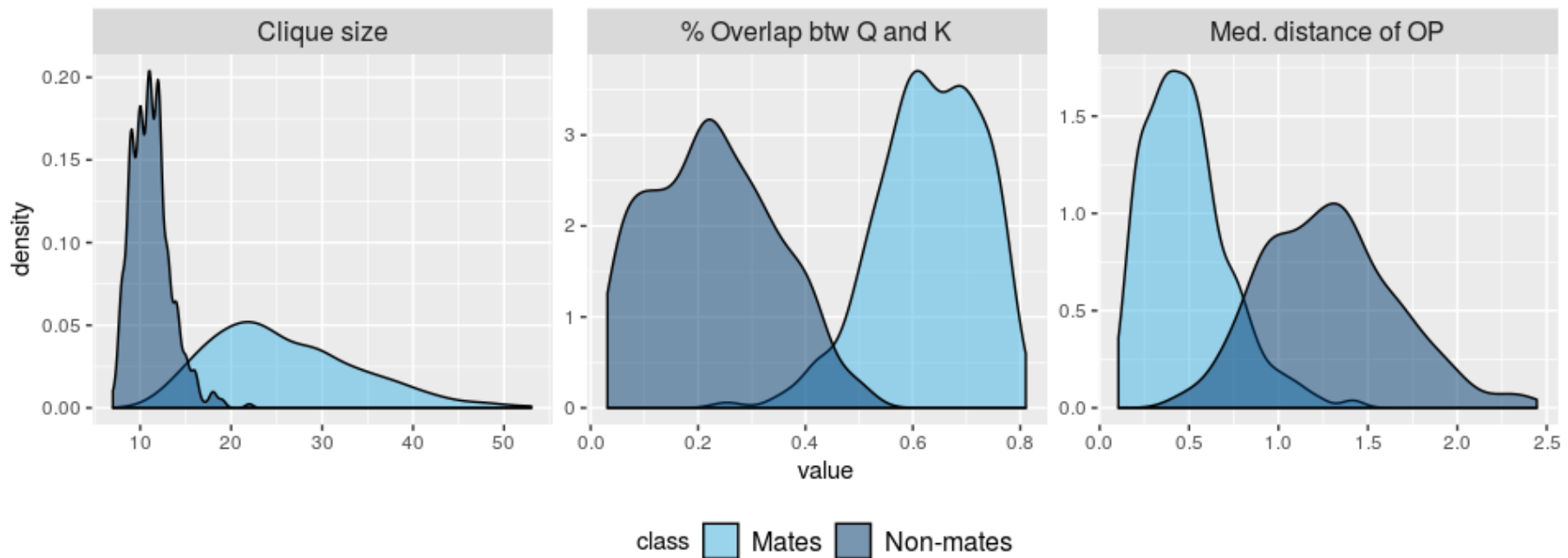
- Size of the MC
- % overlapping points: two points overlap when their distance is 2 pixels or less.
- Median Euclidean distance between overlapping points.
- 501 mated Nike pairs, and 420 non-mated pairs.

Class	Clique size	Rotation angle	% Overlap	Median distance
Mates	18	2.11	56.5%	0.78
Non-mates	9	6.43	12.1%	1.39

# Feature values for M and NM pairs



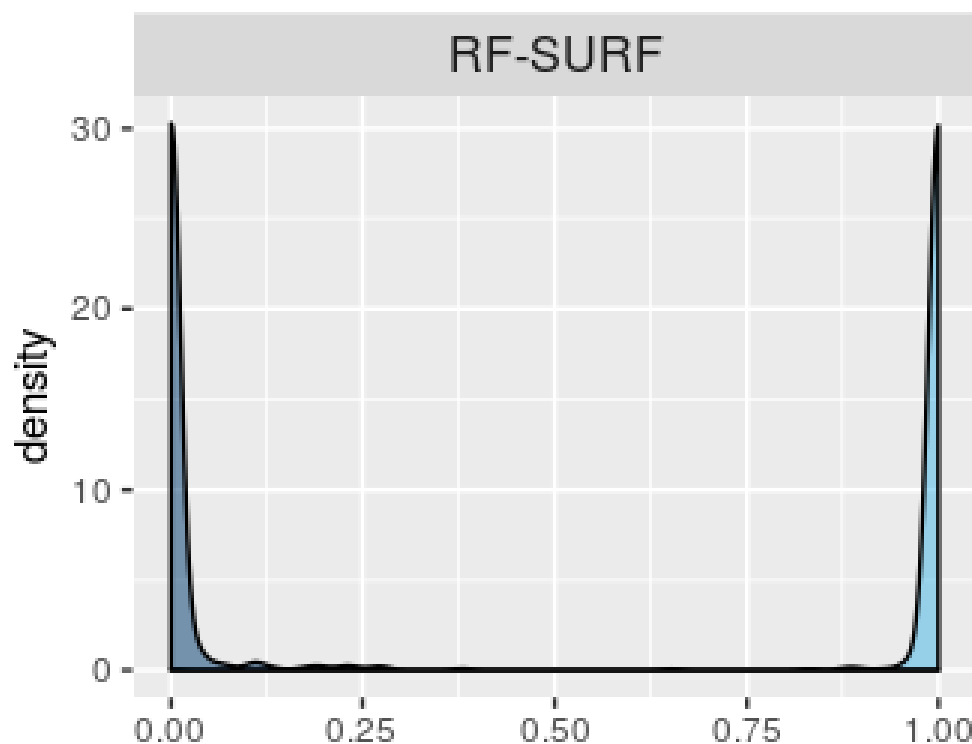
- Can we tell which pairs of images were made by the same or by different shoes?



# Combining features via RF

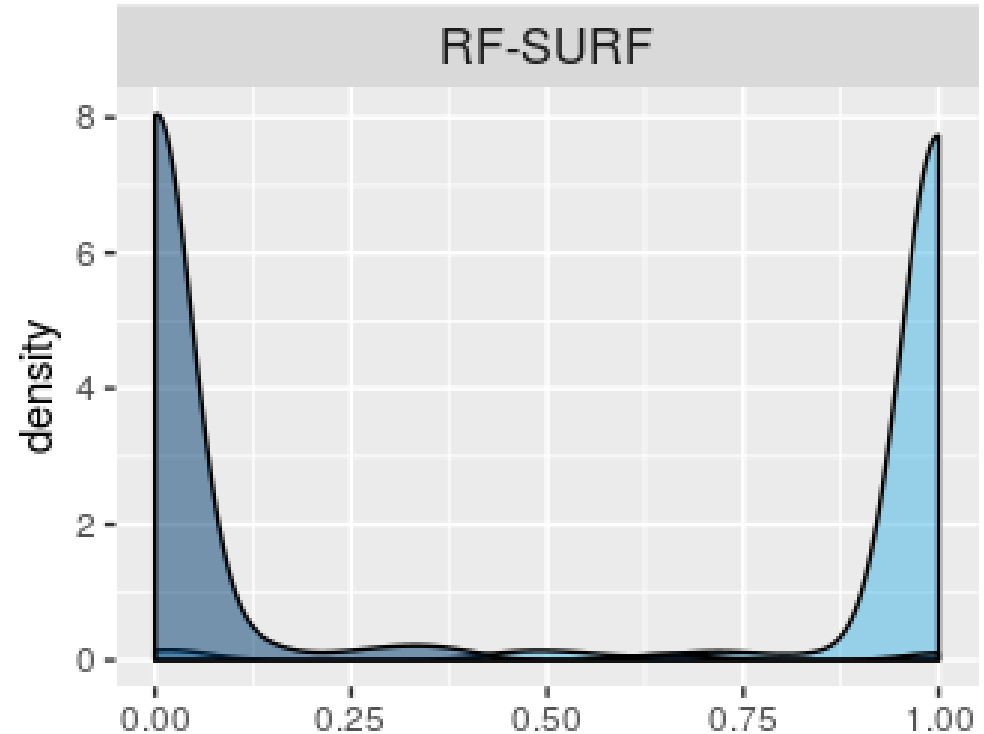


- We can combine features into a single ***similarity score***.
- The score is HIGH when images come from the same shoe.
- Good discrimination!



# When used on a different set of shoes...

- Does the classifier work on a different set of images?
- Yes!
- **False positive rate is 2.2%.**
- **False negative rate is 1.9%.**
- **Overall accuracy: 97.8%.**



# BUT....



- We developed and tested the algorithm using only Nike shoes.
  - **Will the same model be as accurate if we try to classify images from other brands?**
- Both the Q and the K images are of high quality.
  - **Will the performance of the algorithm suffer when Q is degraded or partially observed?**

# Different pattern



- The random forest model was trained and tested on Nike Airflow shoes.
- How will the algorithm work if we present it with images of Adidas Steeley shoes?

Prediction	Images are from same shoe	Images are from different shoes
Predict same shoe	198	0
Predict different shoe	54	210
Total	252	210

# Different pattern



- If we retrain the random forest using a mix of Nike and Adidas shoes, we can improve performance.

Prediction	Images are from same shoe	Images are from different shoes
Predict same shoe	277	8
Predict different shoe	11	196
Total	288	204

- Need to explore whether it is better to have a single model for all shoes or brand-level models.

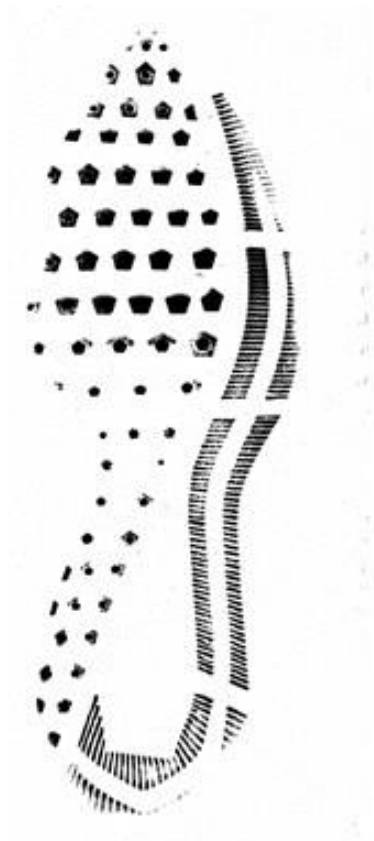
# Degraded images II



- Often, the latent print at the crime scene is blurry or partially observed.
- To test the performance of the algorithm, we degraded the Q image by interposing 2, 4, 6, 8 or 10 sheets of paper between the outsole and the scanner.
- We also deleted about half of the image.
- The K image was still of high quality.



# Degraded images III



# paper = 0



# paper = 2



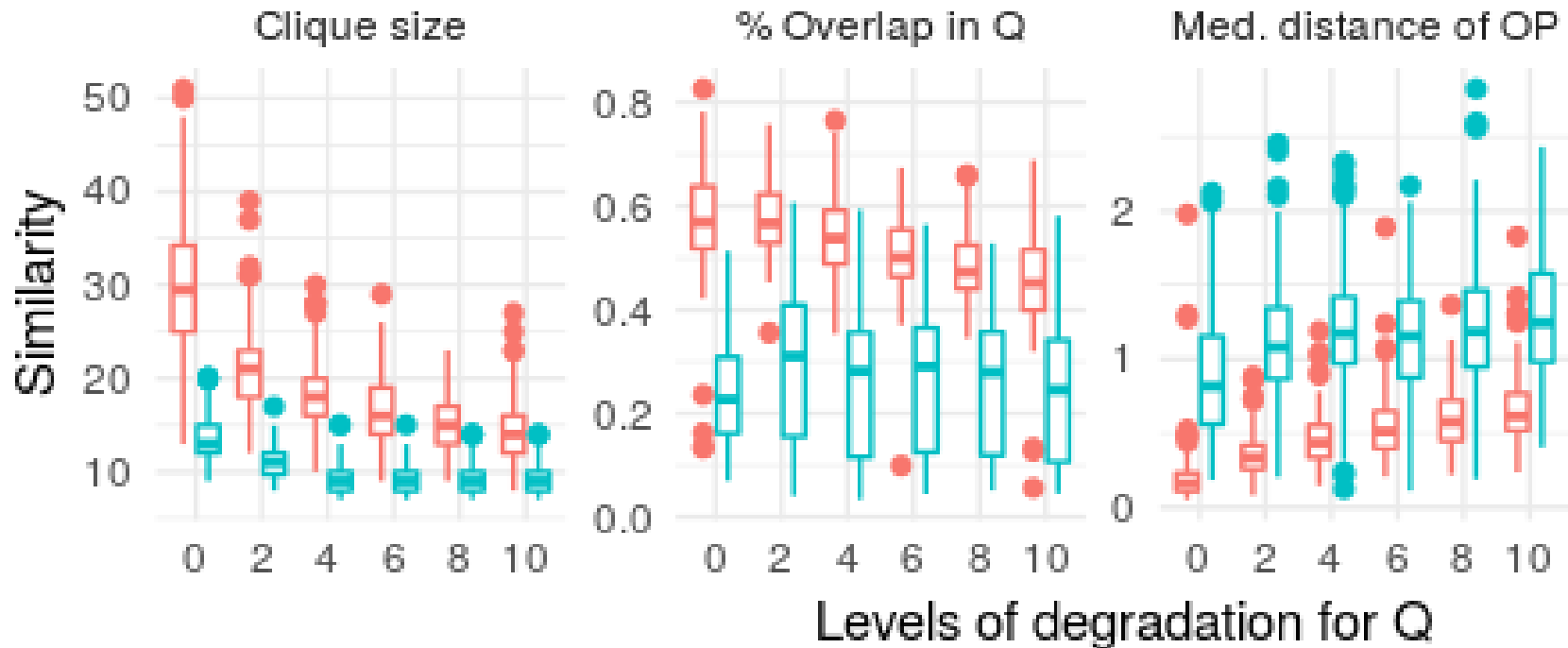
# paper = 6



# paper = 10

# Performance

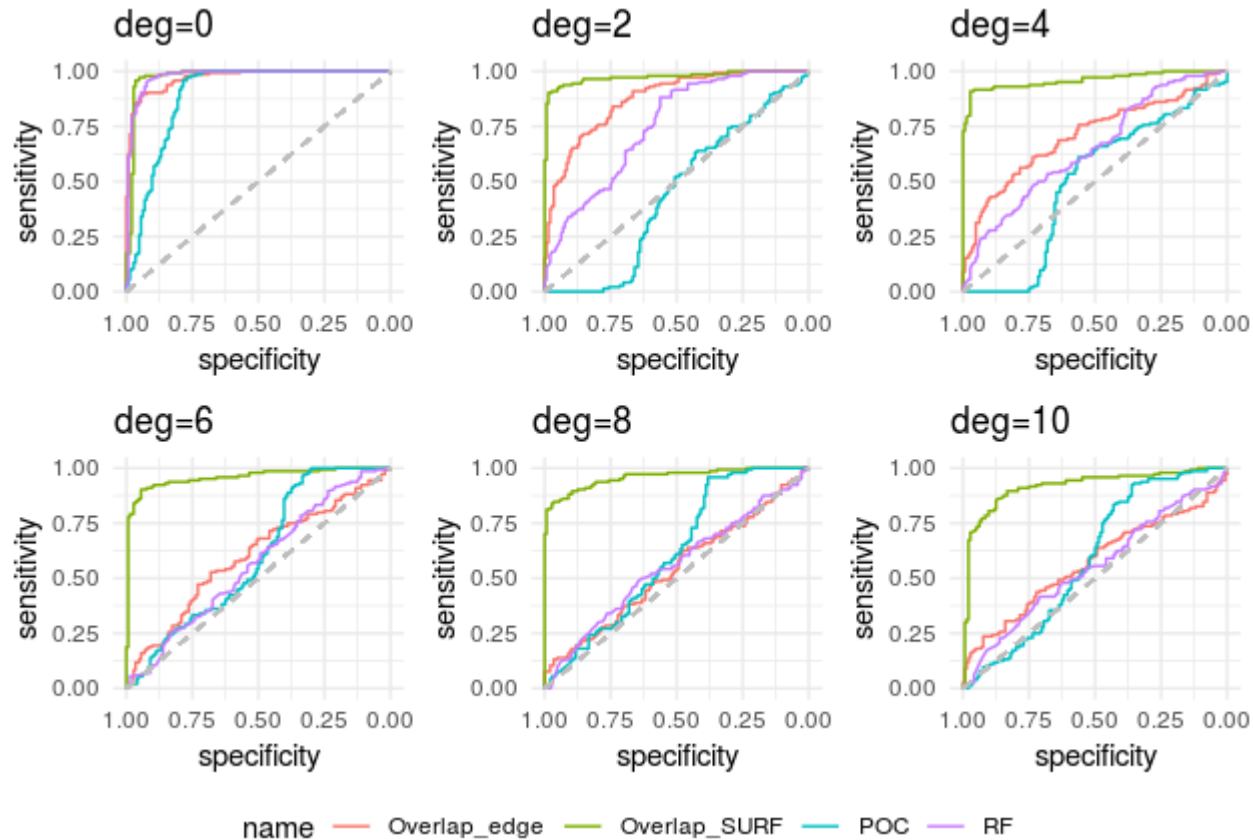
- Red: mates, Blue: non-mates



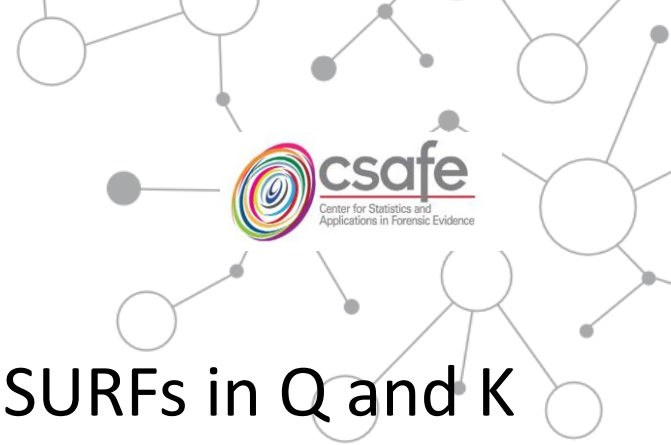
# Performance II



X-axis: True negative rate, Y-axis: True positive rate



# % overlapping SURF



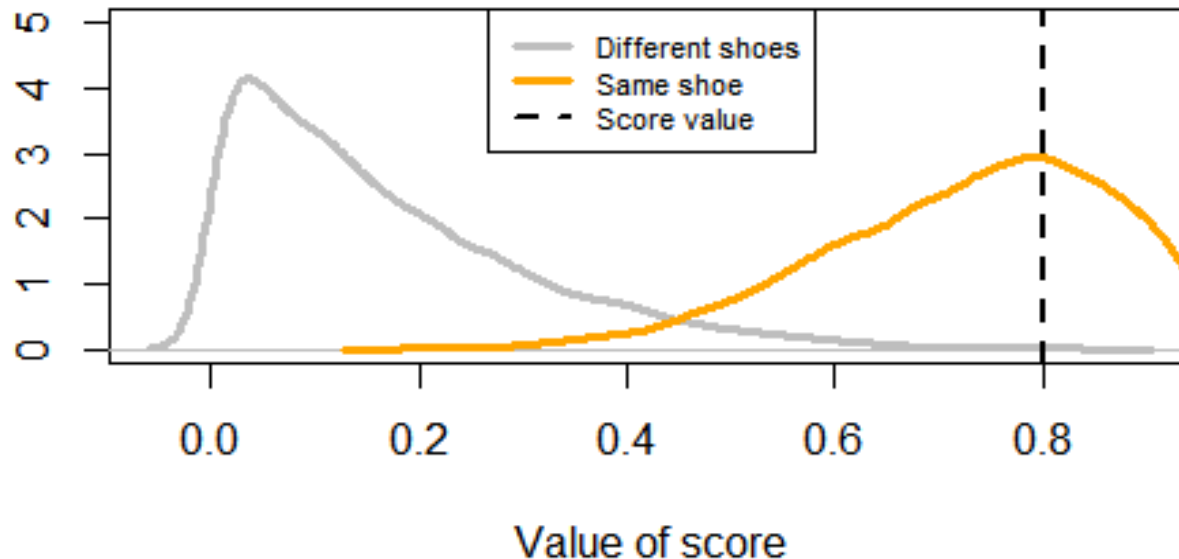
- Classifier that relies only on the % of SURFs in Q and K that overlap appears to be robust to this particular type of image degradation.
- Results for most degraded Q (10 sheets of paper between shoe and scanner):
  - True positive rate: 91% -- Correctly conclude same shoe
  - True negative rate: 97% -- Correctly conclude different shoe
  - **False positive rate: 3% -- Incorrectly conclude same shoe**
  - False negative rate: 9% -- Incorrectly conclude diff shoe

# Probative value of score?



- Looks like we might be able to construct a similarity score with good performance.
- Suppose that in the course of an investigation, we get a pair of prints to compare.
- We compute the similarity score and say we get a value equal to 0.8.
- What does the value tell us? Does it suggest same or different shoe?

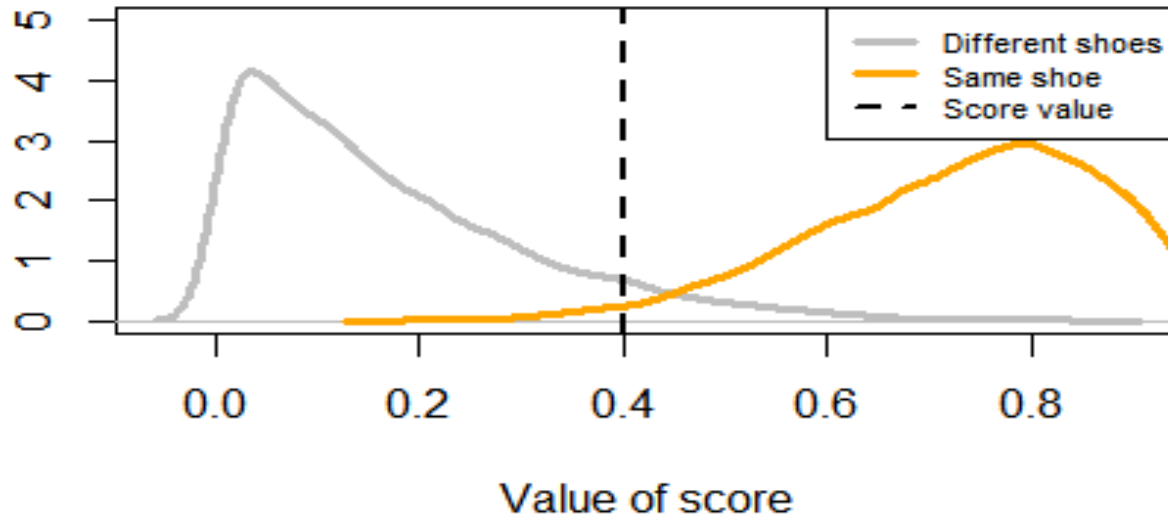
# Score of 0.8



Score-based LR =  $2.8 / 0.008 = 357$ .

It is 357 times more likely to observe a score of 0.8 when images are from the same shoe than when they are not.

# Score of 0.4



Score-based LR =  $0.4 / 1.1 = 0.36$ .

It is 2.7 times more likely to observe a score of 0.4 when images are from different shoes.

# In summary...



- Automatically finding interesting points in an outsole using SURF appears promising.
- When both impressions are of reasonably good quality, an algorithm based on three features has excellent performance, at least for Nike Airflows and Adidas Steeley.
- When Q is degraded, features no longer serve to predict whether Q and K were made by same shoe.
- **Exception is % points that overlap; this feature is robust on degraded and partially observed images.**



# Open questions



- Will algorithms continue to perform well when:
  - We include other brands of shoes (we think yes).
  - Q is degraded in some other way (we need more research).
- What data do we need in order to calculate probative value via SLRs?
- Black-box study: compare the outcome of the automated method to the scores produced by a trained examiner.

# THANKS!



- Please find me at:

[Alicia@iastate.edu](mailto:Alicia@iastate.edu)

- Our website:

[www.forensicstats.org](http://www.forensicstats.org)

- Webinar about pattern evidence research at CSAFE on August 20, at 12:00 CT.